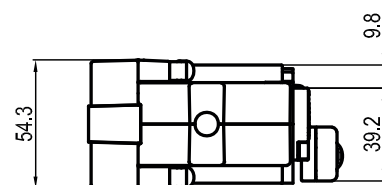
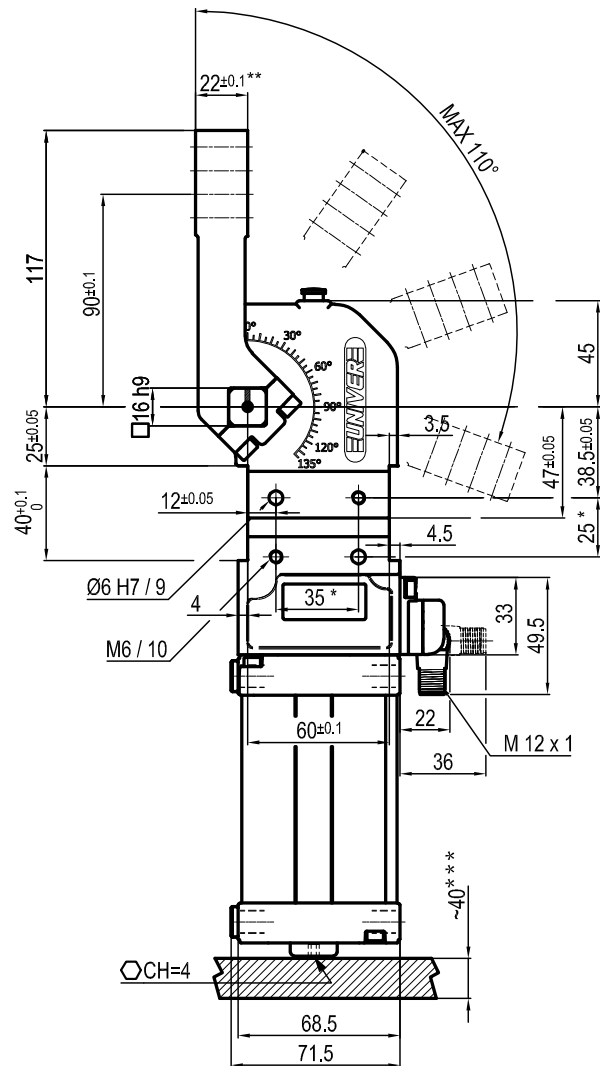
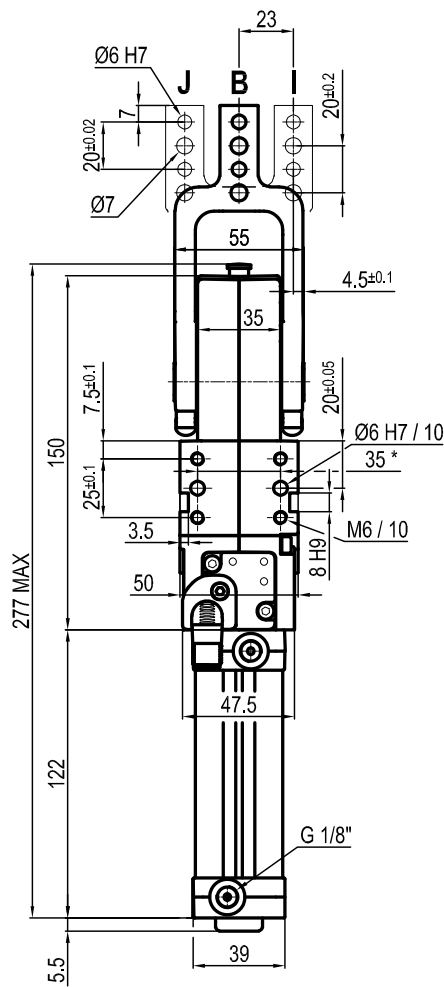


\* : TOLERANCE BETWEEN DOWELS  $\pm 0,02$ , BETWEEN SCREW HOLES  $\pm 0,1$   
 \*\* : AREA TO ACCESS ANGLE ADJUSTMENT

Bore $\varnothing$	Holding moment	Clamping moment (0,5 MPa)	Weight (clamping arm not included)
40 mm	600 Nm	170 Nm	1,5 Kg

Min./Max. operating pressure: **0,4 / 0,6 MPa**  
 Operating temperature: **5° ÷ 45° C**  
 Opening angle: **adjustable**  
 Without arm  
 Electronic sensor with M12 swivel connector, from 0° to 90°  
 Supply voltage: **10 ÷ 30 Vdc**  
 IP code: **IP 65**  
 Pneumatic ports on both sides



\* : TOLERANCE BETWEEN DOWELS  $\pm 0,02$ , BETWEEN SCREW HOLES  $\pm 0,1$   
 \*\* : TOLERANCE AT 80 mm FROM PIVOT POINT  
 \*\*\* : AREA TO ACCESS ANGLE ADJUSTMENT

**UCBP400 \_\_ K0**
**6** ARM STYLE

**7** ARM TYPE

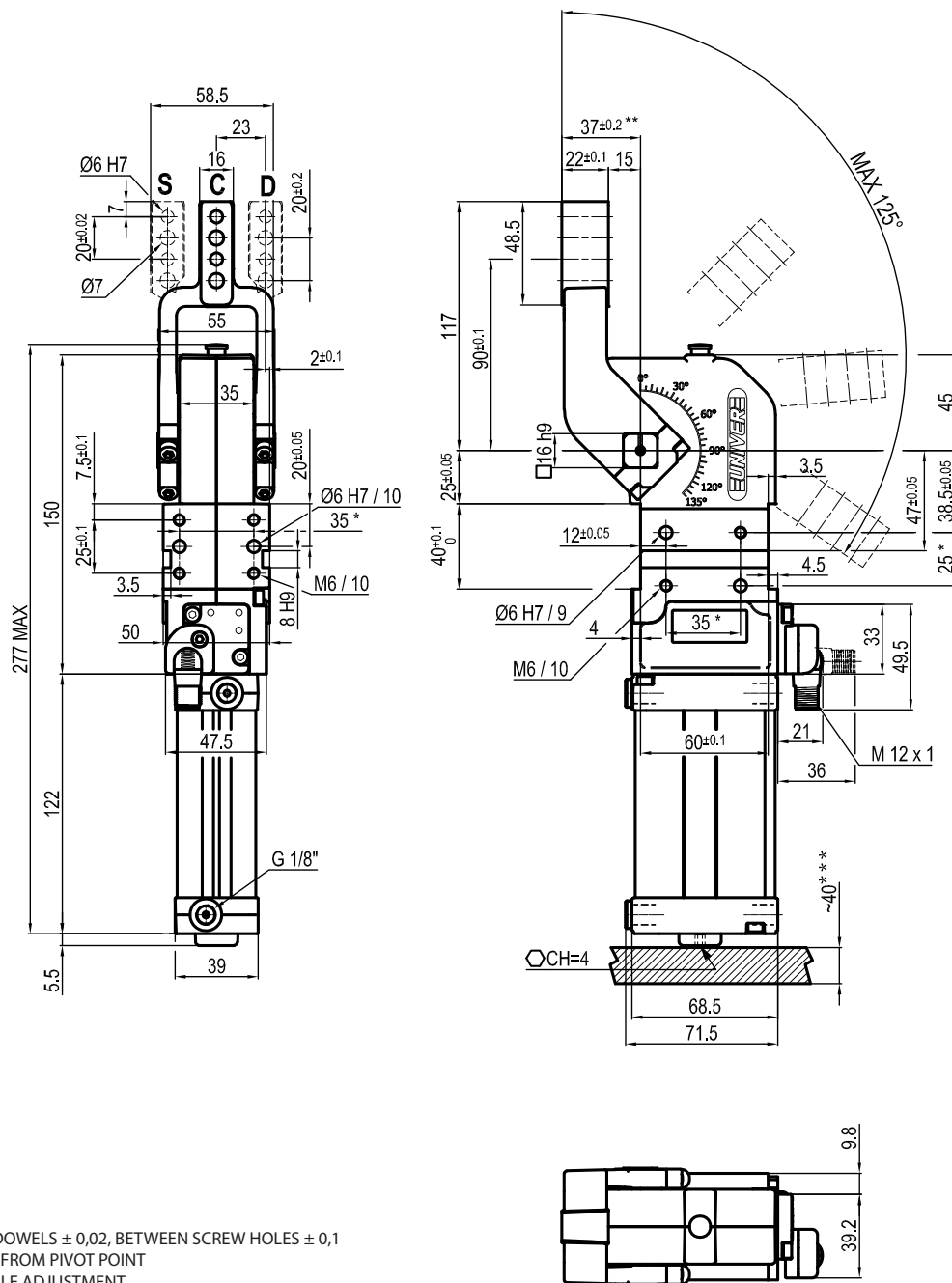
**6 7**

B = Central  
 I = Right  
 J = Left

A = Aluminium  
 S = Steel

Bore $\varnothing$	Holding moment	Clamping moment (0,5 MPa)	Weight (clamping arm not included)
40 mm	600 Nm	170 Nm	1,5 Kg

Min./Max. operating pressure: **0,4 / 0,6 MPa**  
 Operating temperature: **5° ÷ 45° C**  
 Opening angle: **adjustable from 0° to 110°**  
 Arm position: **180°**  
 Electronic sensor with M12 swivel connector, from 0° to 90°  
 Supply voltage: **10 ÷ 30 Vdc**  
 IP code: **IP 65**  
 Pneumatic ports on both sides



\* : TOLERANCE BETWEEN DOWELS ± 0,02, BETWEEN SCREW HOLES ± 0,1  
 \*\* : TOLERANCE AT 80 mm FROM PIVOT POINT  
 \*\*\* : AREA TO ACCESS ANGLE ADJUSTMENT

**UCBP400 \_ \_ K0**
**6 7**
**6** ARM STYLE

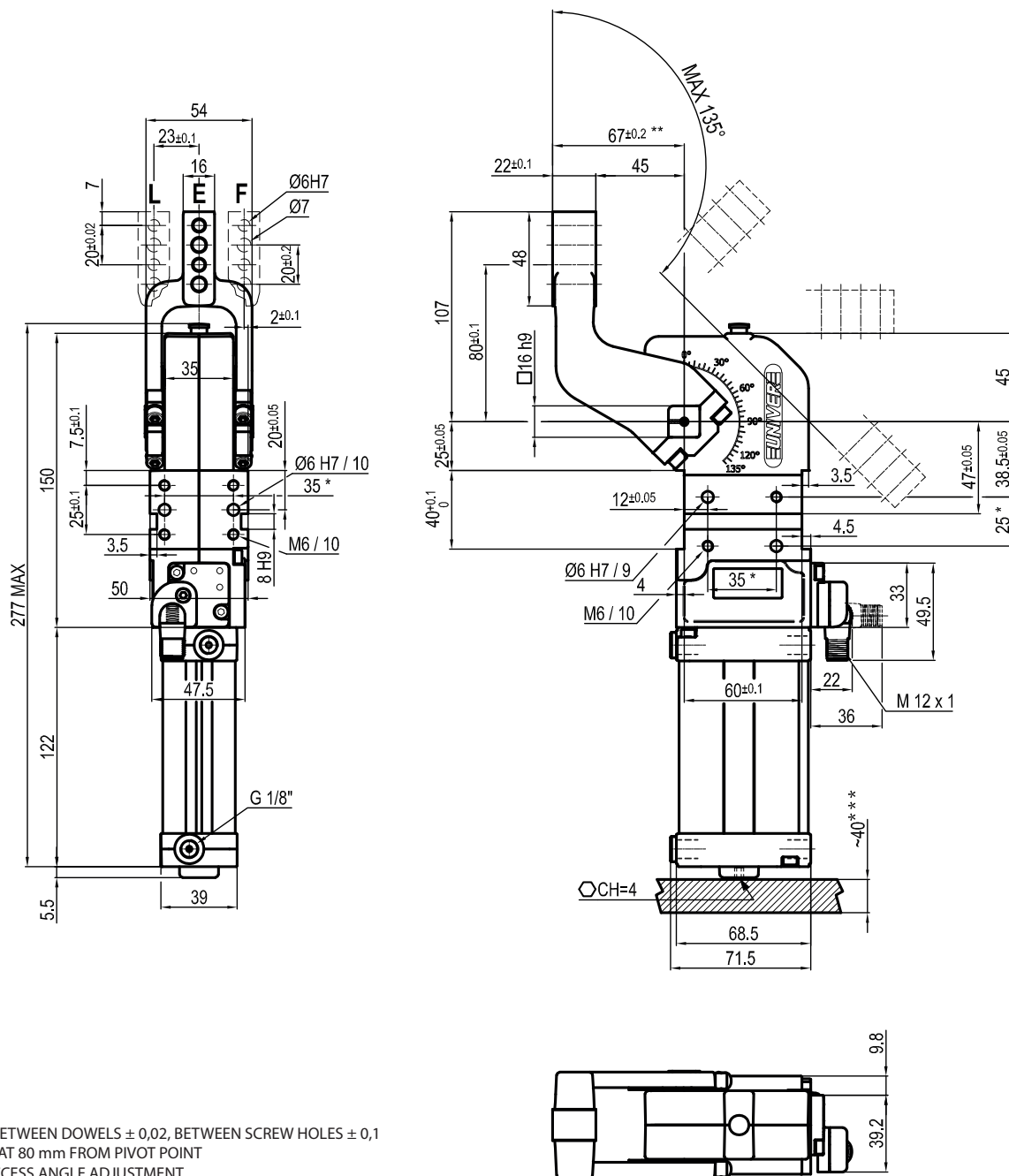
 C = Central  
 D = Right  
 S = Left

**7** ARM TYPE

 A = Aluminium  
 S = Steel

Bore Ø	Holding moment	Clamping moment (0,5 MPa)	Weight (clamping arm not included)
40 mm	600 Nm	170 Nm	1,5 Kg

Min./Max. operating pressure: **0,4 / 0,6 MPa**  
 Operating temperature: **5° ÷ 45° C**  
 Opening angle: **adjustable from 0° to 125°**  
 Arm position: **180°**  
 Electronic sensor with M12 swivel connector, from 0° to 90°  
 Supply voltage: **10 ÷ 30 Vdc**  
 IP code: **IP 65**  
 Pneumatic ports on both sides



\* : TOLERANCE BETWEEN DOWELS ± 0,02, BETWEEN SCREW HOLES ± 0,1  
 \*\* : TOLERANCE AT 80 mm FROM PIVOT POINT  
 \*\*\* : AREA TO ACCESS ANGLE ADJUSTMENT

**UCBP400 \_\_ K0**
**6** ARM STYLE

**7** ARM TYPE

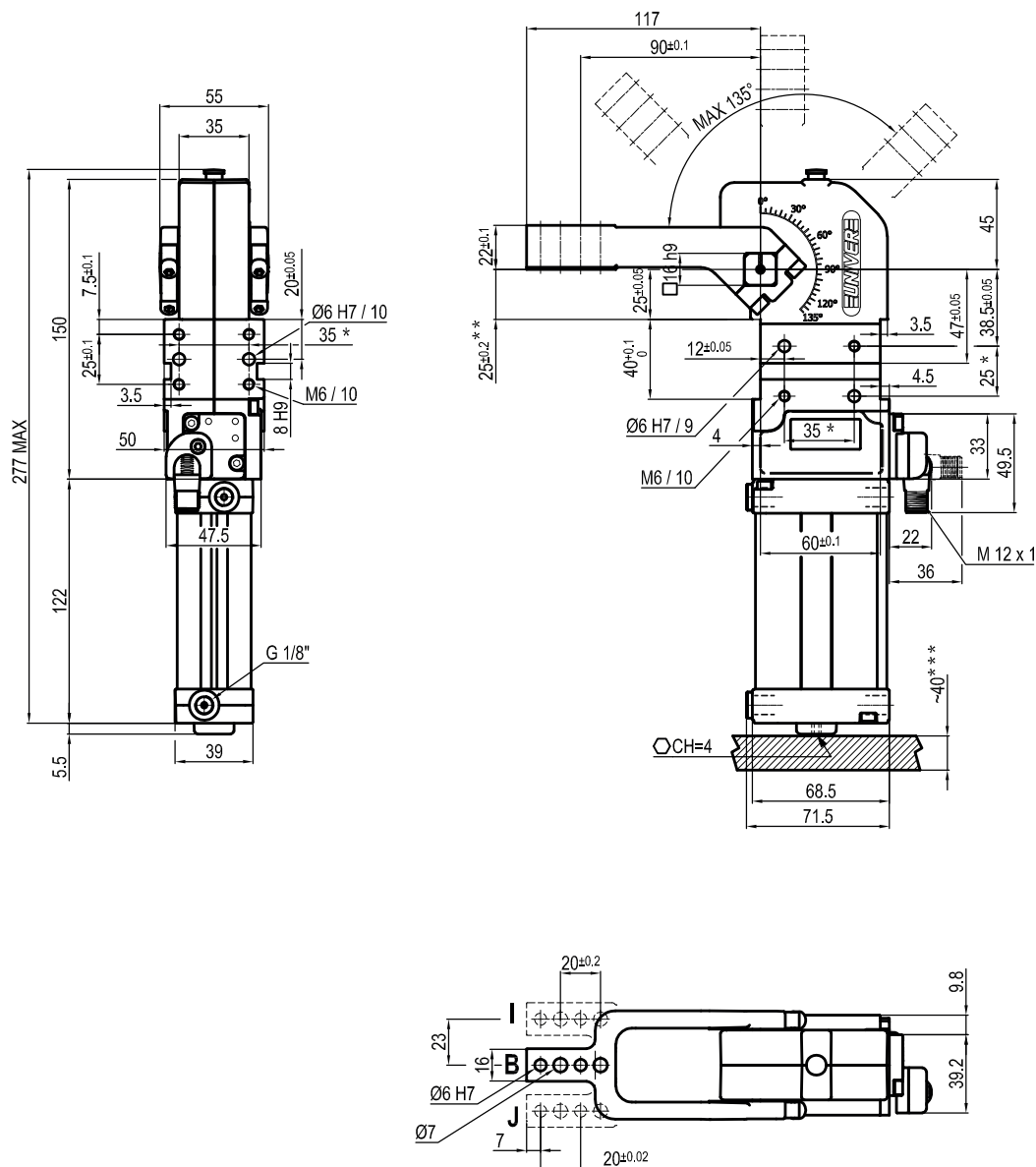
**6 7**

 E = Central  
 F = Right  
 L = Left

 A = Aluminium  
 S = Steel

Bore Ø	Holding moment	Clamping moment (0,5 MPa)	Weight (clamping arm not included)
40 mm	600 Nm	170 Nm	1,5 Kg

Min./Max. operating pressure: **0,4 / 0,6 MPa**  
 Operating temperature: **5° ÷ 45° C**  
 Opening angle: **adjustable from 0° to 135°**  
 Arm position: **180°**  
 Electronic sensor with M12 swivel connector, from 0° to 90°  
 Supply voltage: **10 ÷ 30 Vdc**  
 IP code: **IP 65**  
 Pneumatic ports on both sides



\* : TOLERANCE BETWEEN DOWELS  $\pm 0,02$ , BETWEEN SCREW HOLES  $\pm 0,1$

\*\* : TOLERANCE AT 80 mm FROM PIVOT POINT

\*\*\* : AREA TO ACCESS ANGLE ADJUSTMENT

## UCBP40V \_\_ \_ K0

**6 7**

**6** ARM STYLE

B = Central  
I = Right  
J = Left

**7** ARM TYPE

A = Aluminium  
S = Steel

Bore $\varnothing$	Holding moment	Clamping moment (0,5 MPa)	Weight (clamping arm not included)
40 mm	600 Nm	170 Nm	1,5 Kg

Min./Max. operating pressure: **0,4 / 0,6 MPa**

Operating temperature: **5° ÷ 45° C**

Opening angle: **adjustable from 0° to 135°**

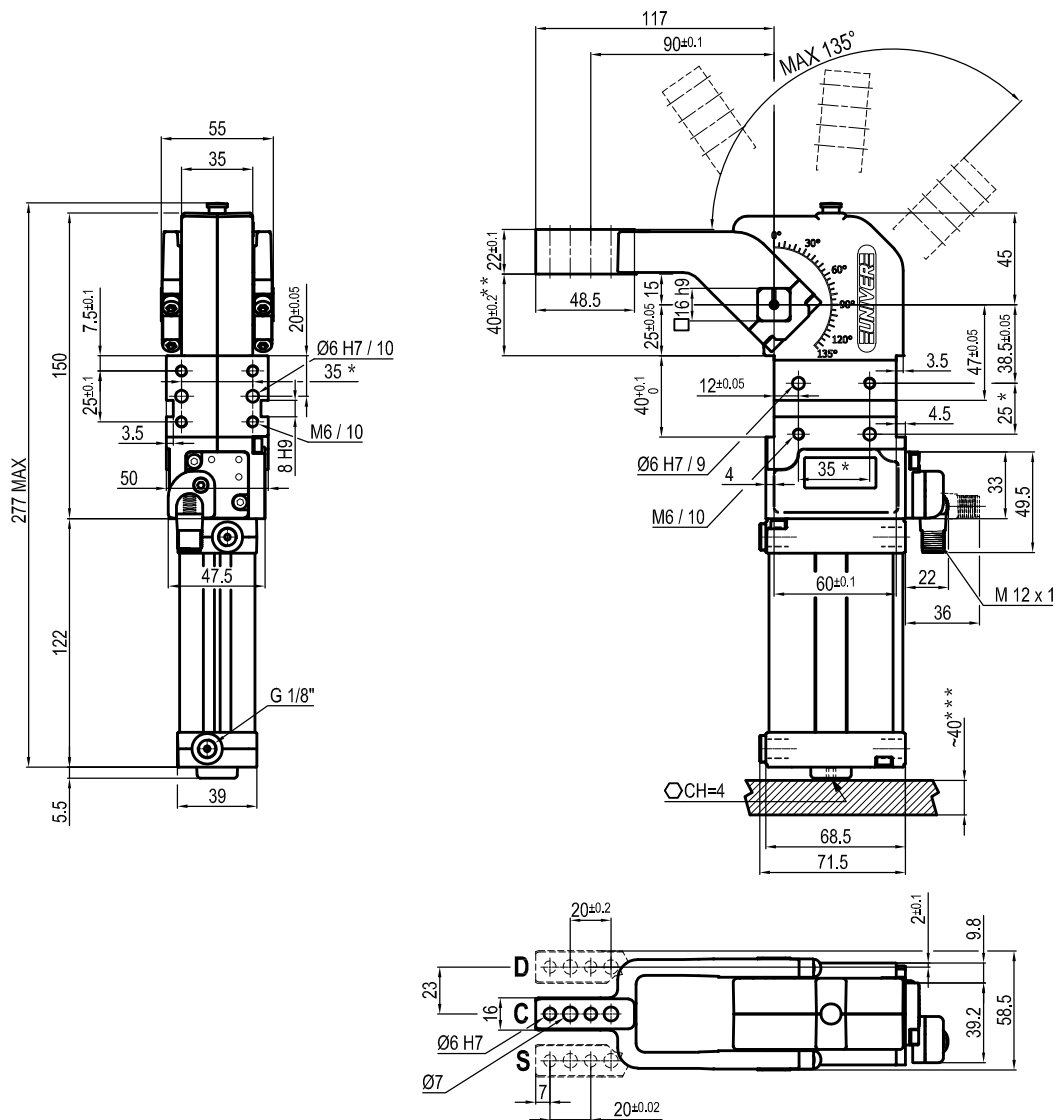
Arm position: **90°**

Electronic sensor with M12 swivel connector, from 0° to 90°

Supply voltage: **10 ÷ 30 Vdc**

IP code: **IP 65**

Pneumatic ports on both sides



\* : TOLERANCE BETWEEN DOWELS  $\pm 0,02$ , BETWEEN SCREW HOLES  $\pm 0,1$

\*\* : TOLERANCE AT 80 mm FROM PIVOT POINT

\*\*\* : AREA TO ACCESS ANGLE ADJUSTMENT

**UCBP40V \_\_ \_ K0**
**6 7**
**6** ARM STYLE

C = Central  
D = Right  
S = Left

**7** ARM TYPE

A = Aluminium  
S = Steel

Bore $\varnothing$	Holding moment	Clamping moment (0,5 MPa)	Weight (clamping arm not included)
40 mm	600 Nm	170 Nm	1,5 Kg

Min./Max. operating pressure: **0,4 / 0,6 MPa**

Operating temperature: **5° ÷ 45° C**

Opening angle: **adjustable from 0° to 135°**

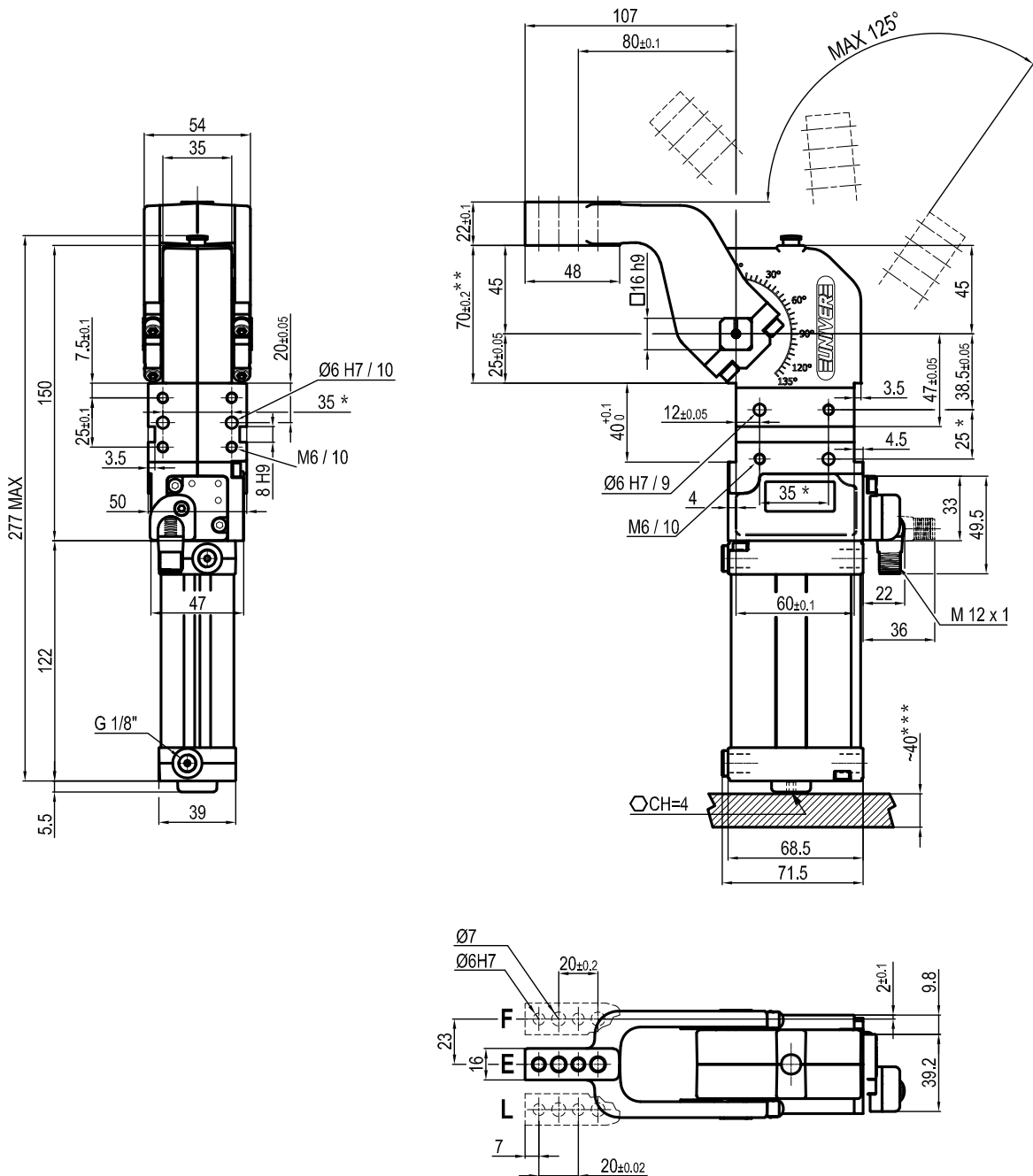
Arm position: **90°**

Electronic sensor with M12 swivel connector, from 0° to 90°

Supply voltage: **10 ÷ 30 Vdc**

IP code: **IP 65**

Pneumatic ports on both sides



\* : TOLERANCE BETWEEN DOWELS  $\pm 0,02$ , BETWEEN SCREW HOLES  $\pm 0,1$   
 \*\* : TOLERANCE AT 80 mm FROM PIVOT POINT  
 \*\*\* : AREA TO ACCESS ANGLE ADJUSTMENT

**UCBP40V \_\_ \_ K0**
**6** ARM STYLE

**7** ARM TYPE

**6 7**

E = Central  
 F = Right  
 L = Left

A = Aluminium  
 S = Steel

Bore $\varnothing$	Holding moment	Clamping moment (0,5 MPa)	Weight (clamping arm not included)
40 mm	600 Nm	170 Nm	1,5 Kg

Min./Max. operating pressure: **0,4 / 0,6 MPa**  
 Operating temperature: **5° ÷ 45° C**  
 Opening angle: **adjustable from 0° to 125°**  
 Arm position: **90°**  
 Electronic sensor with M12 swivel connector, from 0° to 90°  
 Supply voltage: **10 ÷ 30 Vdc**  
 IP code: **IP 65**  
 Pneumatic ports on both sides