

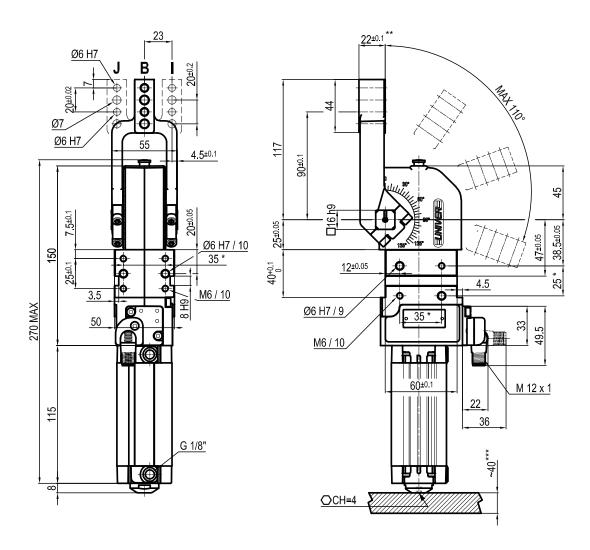
- *: TOLERANCE BETWEEN DOWELS \pm 0.02, BETWEEN SCREW HOLES \pm 0.1
- **: AREA TO ACCESS ANGLE ADJUSTMENT

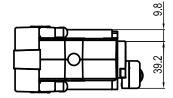
Size Ø	Cylinder bore Ø	Holding moment	Clamping moment (0,5 MPa)	Weight (clamping arm not included)
40 mm	32 mm	600 Nm	125 Nm	1,4 Kg

Min./Max. operating pressure: 0,4 / 0,6 MPa Operating temperature: 5° ÷ 45° C Opening angle: adjustable Without arm

Electronic sensor with M12 swivel connector, from 0° to 90° Supply voltage: $\mathbf{10} \div \mathbf{30 \, Vdc}$







- *: TOLERANCE BETWEEN DOWELS \pm 0.02, BETWEEN SCREW HOLES \pm 0.1
- **: TOLERANCE AT 80 mm FROM PIVOT POINT
- **: AREA TO ACCESS ANGLE ADJUSTMENT

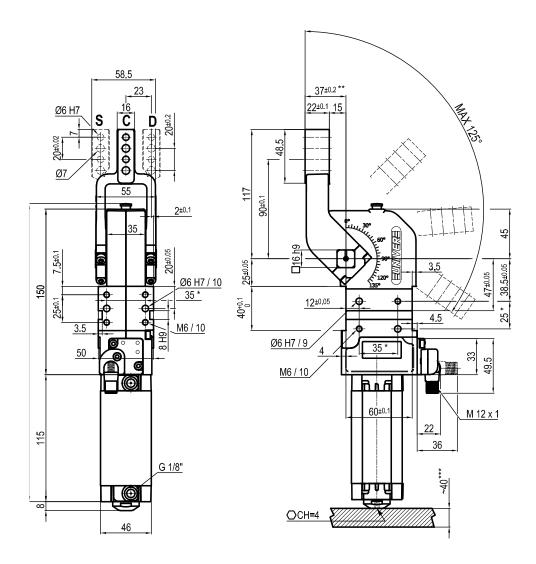
UABP40 O K0	6 ARM STYLE	7 ARM TYPE
6 7	B = Central I = Right	A = Aluminium S = Steel

J = Left

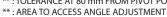
Size	Cylinder bore	Holding	Clamping moment	Weight (clamping arm not included)
Ø	Ø	moment	(0,5 MPa)	
40 mm	32 mm	600 Nm	125 Nm	1,4 Kg

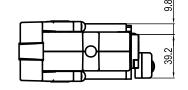
Min./Max. operating pressure: 0,4 / 0,6 MPa
Operating temperature: 5° ÷ 45° C
Opening angle: adjustable from 0° to 110°
Arm position: 180°
Electronic sensor with M12 swivel connector, from 0° to 90°
Supply voltage: 10 ÷ 30 Vdc
IP code: IP 65











UABP40 O K0	6 ARM STYLE	7 ARM TYPE
6 7	C = Central D = Right S = Left	A = Aluminium S = Steel

Size	Cylinder bore	Holding	Clamping moment	Weight
Ø	Ø	moment	(0,5 MPa)	(clamping arm not included)
40 mm	32 mm	600 Nm	125 Nm	

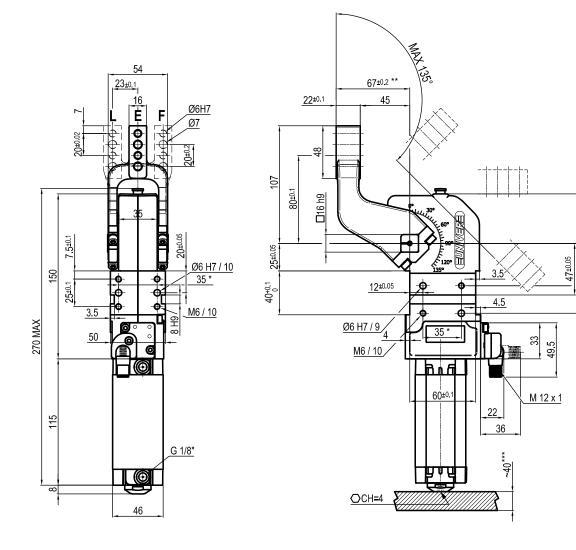
Min./Max. operating pressure: 0,4 / 0,6 MPa
Operating temperature: 5° ÷ 45° C
Opening angle: adjustable from 0° to 125°
Arm position: 180°
Electronic sensor with M12 swivel connector, from 0° to 90°
Supply voltage: 10 ÷ 30 Vdc
IP code: IP 65

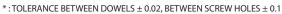


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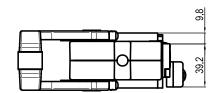
38,5±0.05

25 *





^{**:} TOLERANCE AT 80 mm FROM PIVOT POINT



UABP40 O K0	6 ARM STYLE	7 ARM TYPE
6 7	E = Central F = Right	A = Aluminium S = Steel

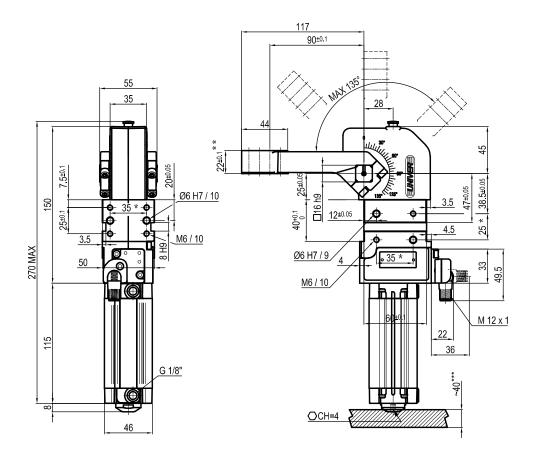
L = Left

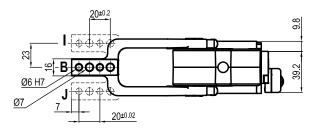
Size Ø	Cylinder bore Ø	Holding moment	Clamping moment (0,5 MPa)	Weight (clamping arm not included)
40 mm	32 mm	600 Nm	125 Nm	1,4 Kg

Min./Max. operating pressure: 0,4 / 0,6 MPa
Operating temperature: 5° ÷ 45° C
Opening angle: adjustable from 0° to 135°
Arm position: 180°
Electronic sensor with M12 swivel connector, from 0° to 90°
Supply voltage: 10 ÷ 30 Vdc
IP code: IP 65

^{**:} AREA TO ACCESS ANGLE ADJUSTMENT







- *: TOLERANCE BETWEEN DOWELS \pm 0.02, BETWEEN SCREW HOLES \pm 0.1
- ** : TOLERANCE AT 80 mm FROM PIVOT POINT
- **: AREA TO ACCESS ANGLE ADJUSTMENT

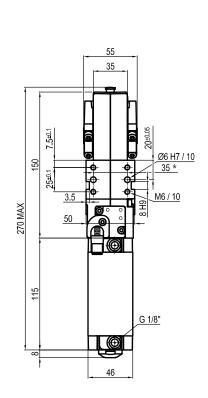
UABP40 V K0	6 ARM STYLE	7 ARM TYPE
	D. Control	A Alumainiu

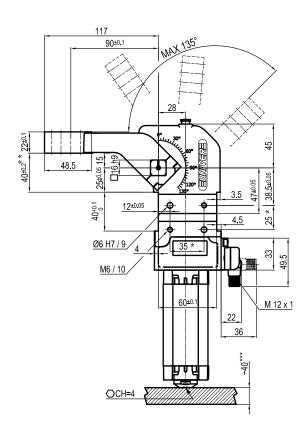
 $\begin{array}{ccc} \textbf{7} & \textbf{B} = \mathsf{Central} & \textbf{A} = \mathsf{Aluminium} \\ \textbf{I} = \mathsf{Right} & \textbf{S} = \mathsf{Steel} \\ \textbf{J} = \mathsf{Left} & \end{array}$

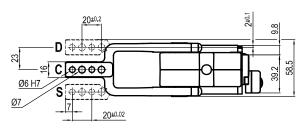
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Ø	Ø	moment	(0,5 MPa)	
40 mm	32 mm	600 Nm	125 Nm	1,4 Kg

Min./Max. operating pressure: 0,4 / 0,6 MPa
Operating temperature: 5° ÷ 45° C
Opening angle: adjustable from 0° to 135°
Arm position: 90°
Electronic sensor with M12 swivel connector, from 0° to 90°
Supply voltage: 10 ÷ 30 Vdc









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- **: TOLERANCE AT 80 mm FROM PIVOT POINT
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UABP40V	_	_ K0	
	_	_	

0	ARM	ST	YLE	

7 ARM TYPE

6 7

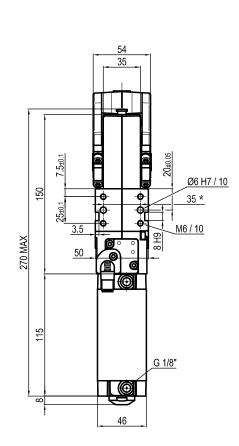
C = Central D = Right S = Left **A** = Aluminium **S** = Steel

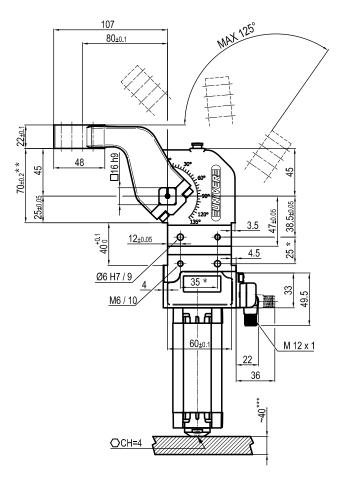
Size	Cylinder bore	Holding	Clamping moment	Weight (clamping arm not included)
Ø	Ø	moment	(0,5 MPa)	
40 mm	32 mm	600 Nm	125 Nm	1,4 Kg

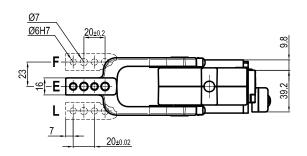
Min./Max. operating pressure: 0,4 / 0,6 MPa Operating temperature: 5° ÷ 45° C Opening angle: adjustable from 0° to 135° Arm position: 90° Electronic sensor with M12 swivel connector. fi

Electronic sensor with M12 swivel connector, from 0° to 90° Supply voltage: $10 \div 30 \, Vdc$









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40 mm	32 mm	600 Nm	125 Nm	1,4 Kg

L = Left

Min./Max. operating pressure: 0,4 / 0,6 MPa Operating temperature: 5° ÷ 45° C Opening angle: adjustable from 0° to 125° Arm position: 90° Electronic sensor with M12 swivel connector, fi

Electronic sensor with M12 swivel connector, from 0° to 90° Supply voltage: ${\bf 10 \div 30~Vdc}$